

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	3	(sensor near6 offset near6 correct\$6)and (yaw near6 rate)and (roll near6 rate)and (longitudinal near6 acceleration)and (lateral near6 acceleration)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 11:22
L2	3	("5610575" "5825284" "5890084").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2004/11/29 11:15
L3	3	((sensor near6 offset)same correct\$6)and (yaw near6 rate)and (roll near6 rate)and (longitudinal near6 acceleration)and (lateral near6 acceleration)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 11:34
L4	24	("6192305").URPN.	USPAT	OR	OFF	2004/11/29 11:23
L5	88	((sensor near6 offset)same correct\$6)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 11:36
L6	44	(sensor near6 offset near5 correct\$6)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:41
L7	63	((sensor near6 offset)same correct\$6)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start\$5 or starting or moving or stop or stopping)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:32
L8	63	((sensor near6 offset)same correct\$6)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start\$5 or starting or moving or stop or stopping or (standing near6 still))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 11:38
L9	10	("4914564" "5382206" "5454442" "5602732" "5623408" "5719790" "5732379" "5979581" "6317674" "6377906").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2004/11/29 11:44
L10	9	("5001636" "5102162" "5270960" "5274576" "5321616" "5333058" "5388658" "5502639" "5524079").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2004/11/29 11:58

L12	13	("5719790").URPN.	USPAT	OR	OFF	2004/11/29 11:58
L13	16	("4927170" "5123497" "5225753" "5274576" "5285390" "5311431" "5347458" "5448481" "5608631" "5642281" "5719790" "5742918" "5742919" "5809434" "5815825" "5857160").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2004/11/29 12:08
L14	1	(sensor same offset same correct\$6)and (roll same rate same compensat\$6)and initialization and (road same bank same angle)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:33
L15	6	(sensor same offset same correct\$6) and (road same bank same angle)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:39
L16	20	(sensor same offset) and (road same bank same angle)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:39
L17	7	(sensor near6 offset near5 correct\$6)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (temperature same drift same rate)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:43
L18	15	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and initialization and (filter same roll same rate)and (filter same yaw same rate)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:46
L19	190	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start or stop or (stand same still))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:47
L20	213	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start or stop or rest or (stand near6 still))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:54

L21	122	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start or stop or rest or (stand near6 still))and (pitch or roll)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:54
L22	39	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start or stop or rest or (stand near6 still))and (pitch near6 angle)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:55
L23	28	(sensor near6 offset)and ((yaw near6 rate)or (roll near6 rate)or (longitudinal near6 acceleration)or (lateral near6 acceleration)) and (start or stop or rest or (stand near6 still))and (pitch near6 angle)and (roll near6 rate)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2004/11/29 12:55